



Picosat Systems

Development of OzQube-1

Stuart McAndrew

1st Asian PocketQube Workshop

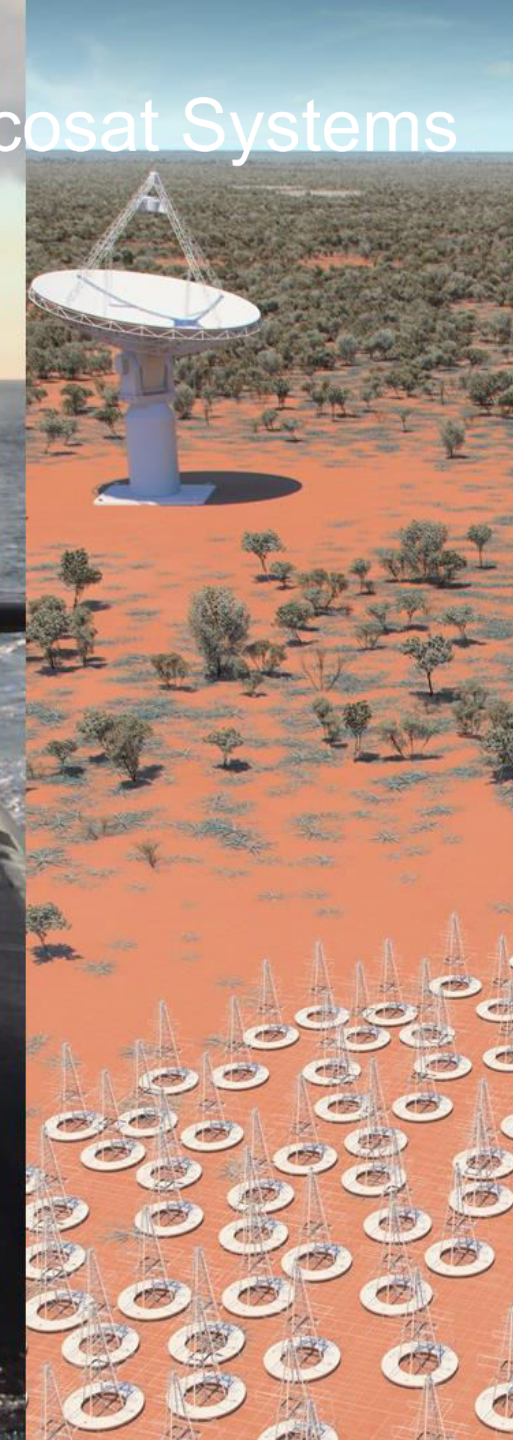
5th Nov 2018



Who are we?

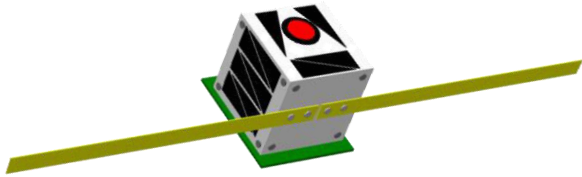


- Small early-stage startup based in Perth, Western Australia
- Co-founders: Stuart McAndrew and Conrad Pires
- Aim to develop space industry in Australia
- Focussing on new, small form factor satellites, including PocketQubes and Cubesats



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Concept



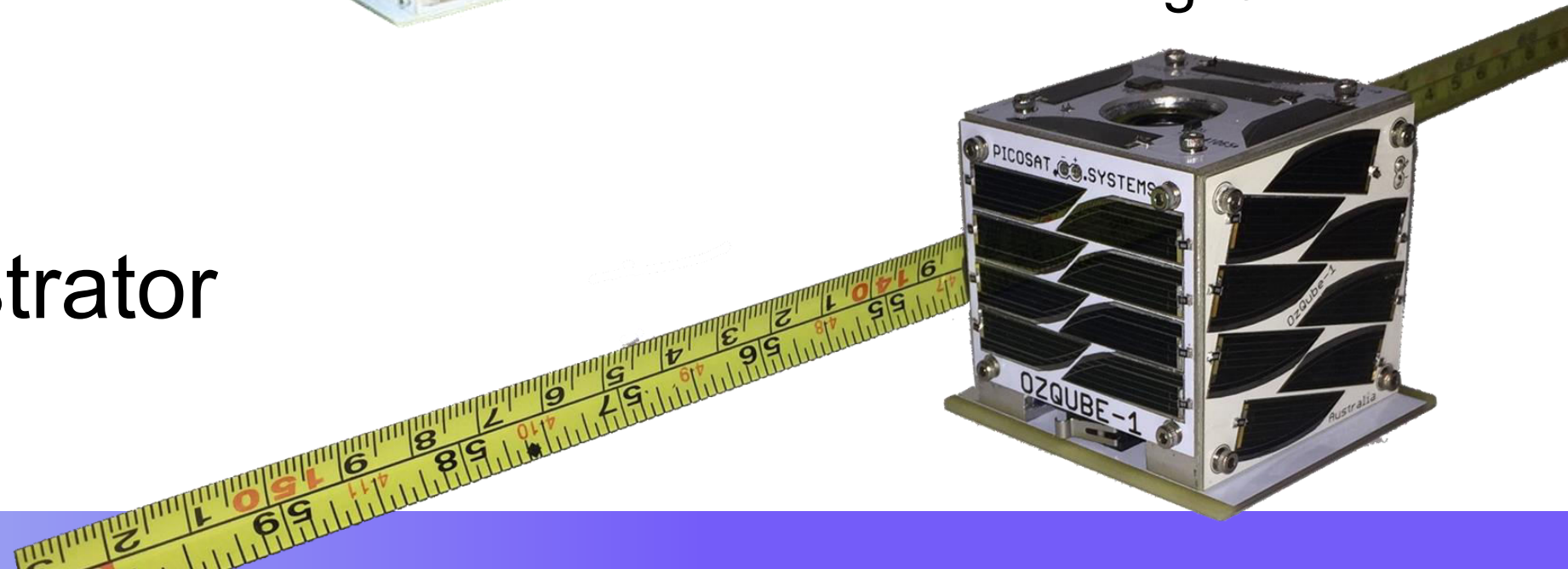
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Engineering



Flight

OzQube-1
Tech Demonstrator





A 1P PocketQube designed and built in (Western) Australia.

Main Mission Objectives:

- Validate core PocketQube subsystems (CDH, Comms, EPS)
- Capture colour images of Australia from space
- Transmit the images to people around the world

OzQube-1

Pico-satellite Technology Demonstrator
Mission: Capture colour images of Australia

Size: 5cm x 5cm x 5cm (excluding antenna)

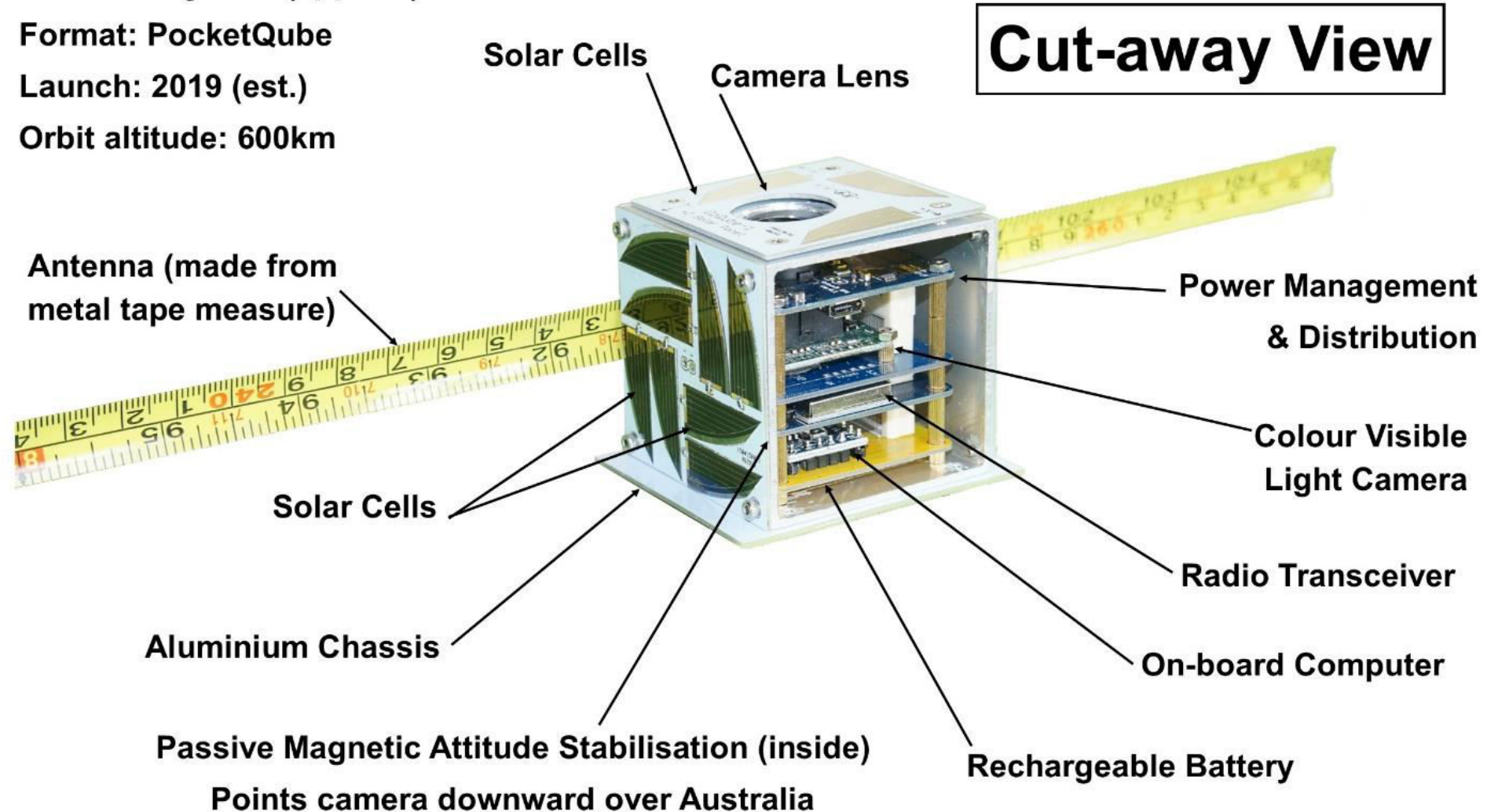
Mass: 150 grams (approx.)

Format: PocketQube

Launch: 2019 (est.)

Orbit altitude: 600km

Antenna (made from
metal tape measure)





Key Features

- PQ60(ish) inside
- Separate PCB's for each subsystem (EPS, CDH, Comms, Camera payload)
- Simplified robust design
- Single Li-ion 800mAh (ish) cell (sandwiched between PCB's)
- Tape measure antenna



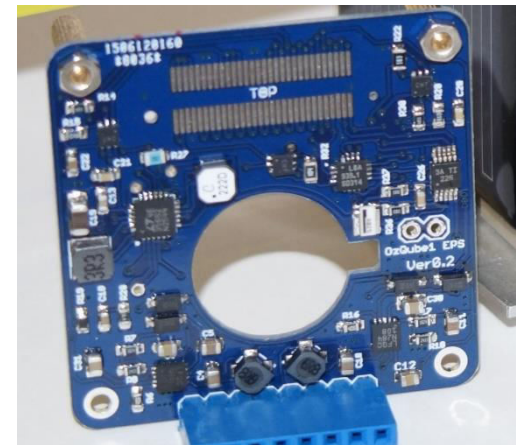
Command & Data Handling

- ATmega1284P Microcontroller (Was ATmega328p but needed more!)
- μ SD and FRAM Data storage
- 9-Axis IMU (Only 6 useful in orbit!)
- External Watchdog
- RTC
- Connects to comms via SPI + GPIO, EPS via I2C + direct GPIO



EPS

- Hole in the middle for camera lens
- 4 channel MPPT(+X, -X, -Y separate, +Z and -Z on single channel with blocking diodes on each panel)
- Single BCR (Battery Charge Regulator)
- Temp controlled Battery charging
- PowerPath for battery bus (Maintains 3.6V if battery failed or low)
- 3.3V Bus and 1 switched 3.3v circuit for payload (that's why PQ60ish)
- All power circuits have current limiting and overload protection
- V + I telemetry from Bat and BCR output (not per panel as board space is limited!)

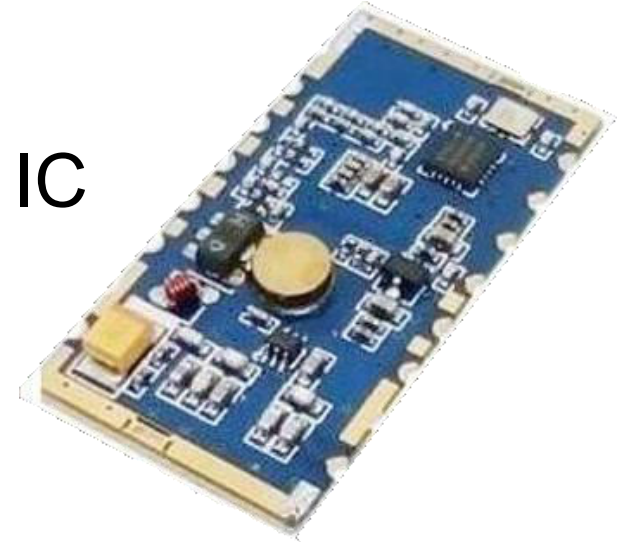


EPS Prototype



Comms

- Radio based on Silicon Labs Si4463 transceiver IC
- 70cm Amateur band
- Half-wave dipole tape measure antenna
- 1W / 30dBm output
- FSK 9600bps / 19200kbps
- Custom packet format (to be released before launch)
- Open uplink commands available to HAM operators (such as RSSI report, Telemetry dump)
- Reception with Arduino and Si4463 based radio (eg, RFM26W)
Software based on RadioHead driver.



Camera

- Off-the-shelf UART camera – Slightly modified
- Originally planned 2Mp, but 5Mp version now available!
- OV5642 + STM32 Micro
- Adapted to PQ60 board
- 25mm M12 Lens
- GSD
 - 34m @ 600km
 - 17m @ 300km
- JPEG images





ADCS

- Passive Magnetic Stabilisation
- Dual magnets to provide improved stability around roll axis
- Pointing downwards over southern hemisphere & Nadir over Australia
- No active control (Yet.....)
- Photodiode based sun sensor for basic solar angle determination
- Will experiment with images of stars to determine position



Lessons Learnt (so far)

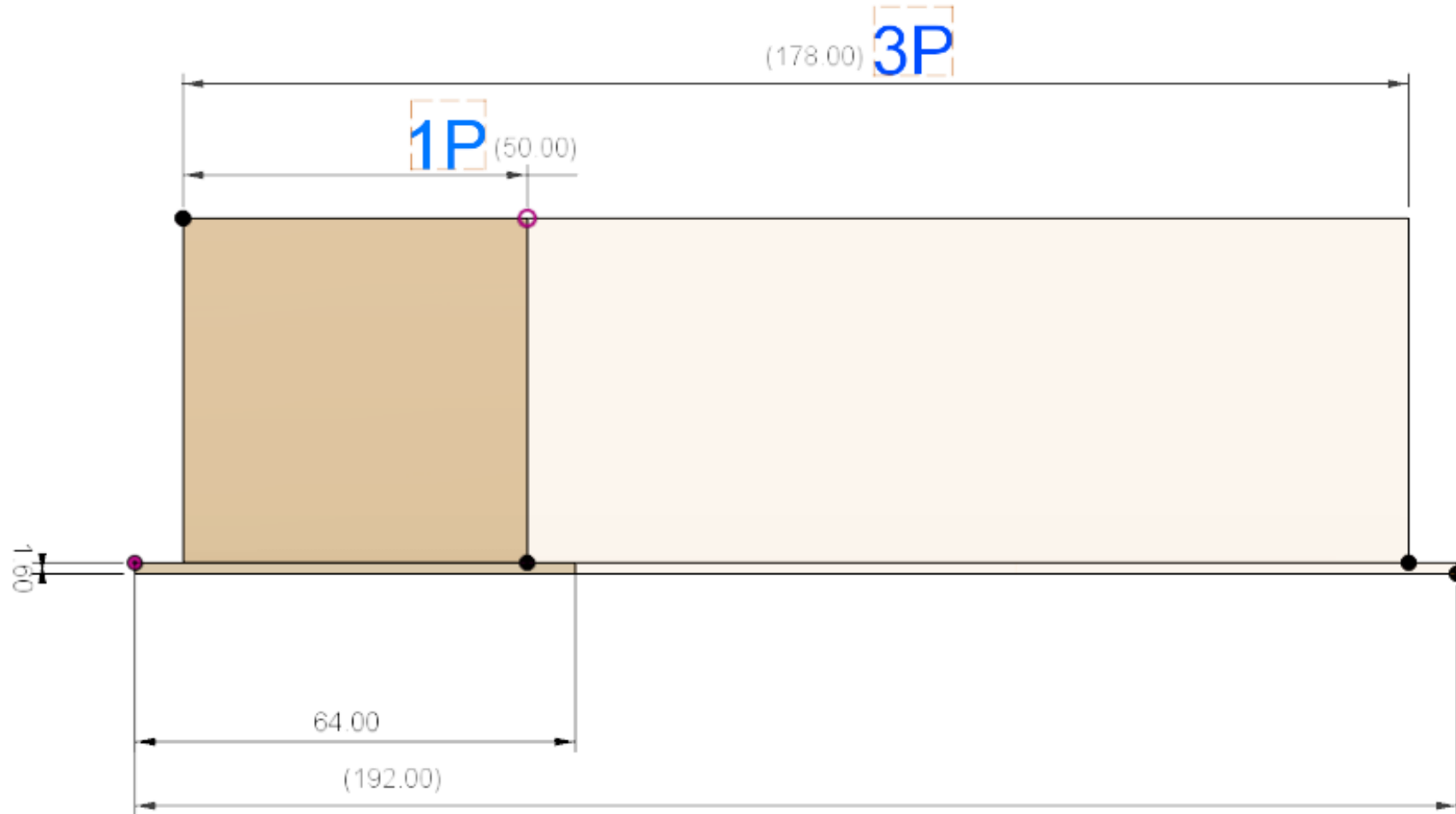
- Easy to get scope creep (Try and stick to the plan)
- Lots and lots of little things matter
- There's always more to learn
- Radios are black holes of knowledge
- Some things are more expensive than you think (I'm talking about you conductive epoxy.....)

What's Next?

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Platform Evolution





Technology Evolution

Deployable Solar (15 W, ~10W OAP)

High Power EPS

S-band 2Mbps

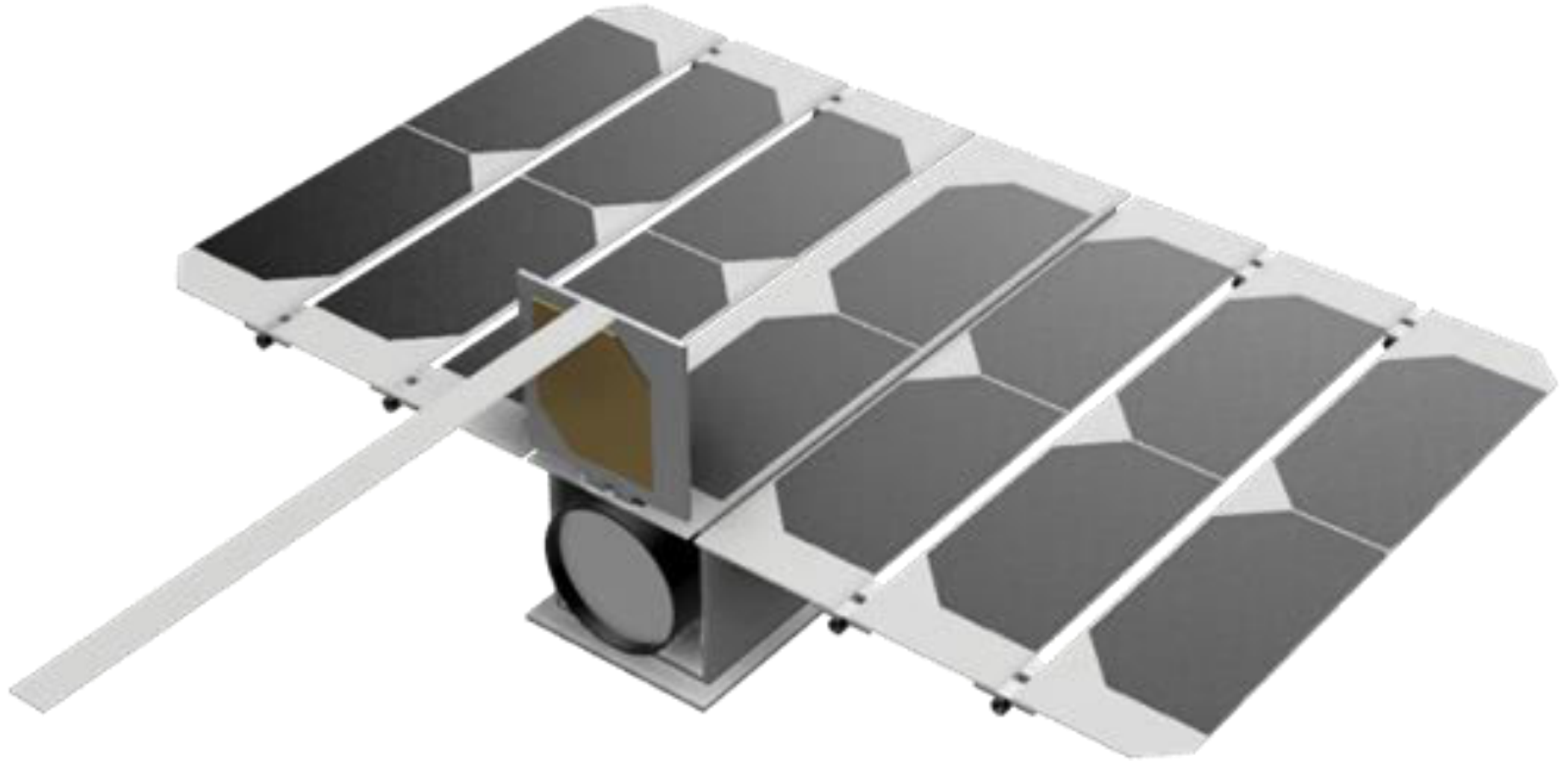
Mesh and Delay Tolerant networking

Evolved Star Tracker

Reflectarray Antenna

Optical Comms

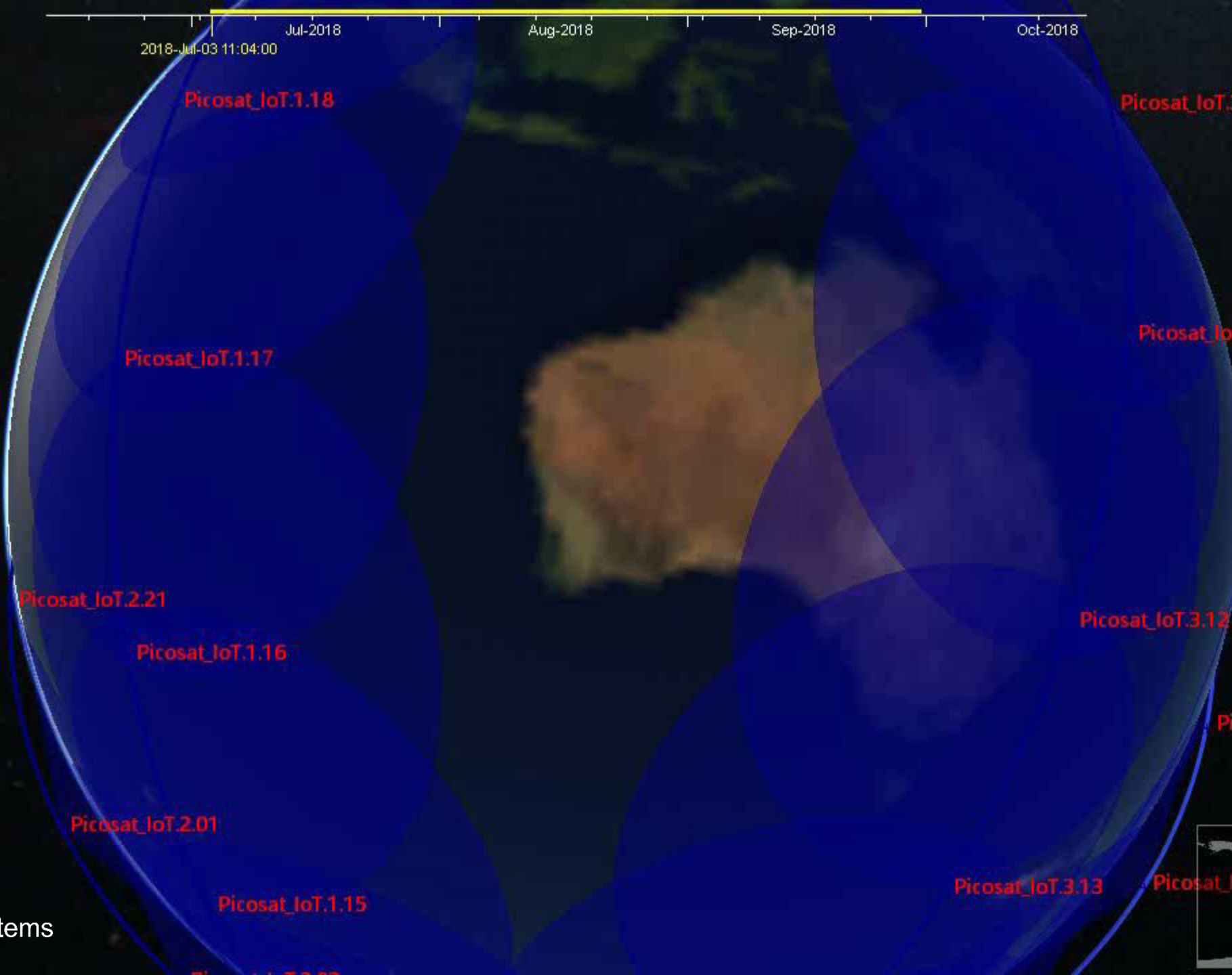
Commercial Platform



3P Picosatellite

2018-Jul-03 11:03:52 UTC

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Lon :
MLST :
SZA :
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Altitude : 7351.4 km
Height : 0 meters
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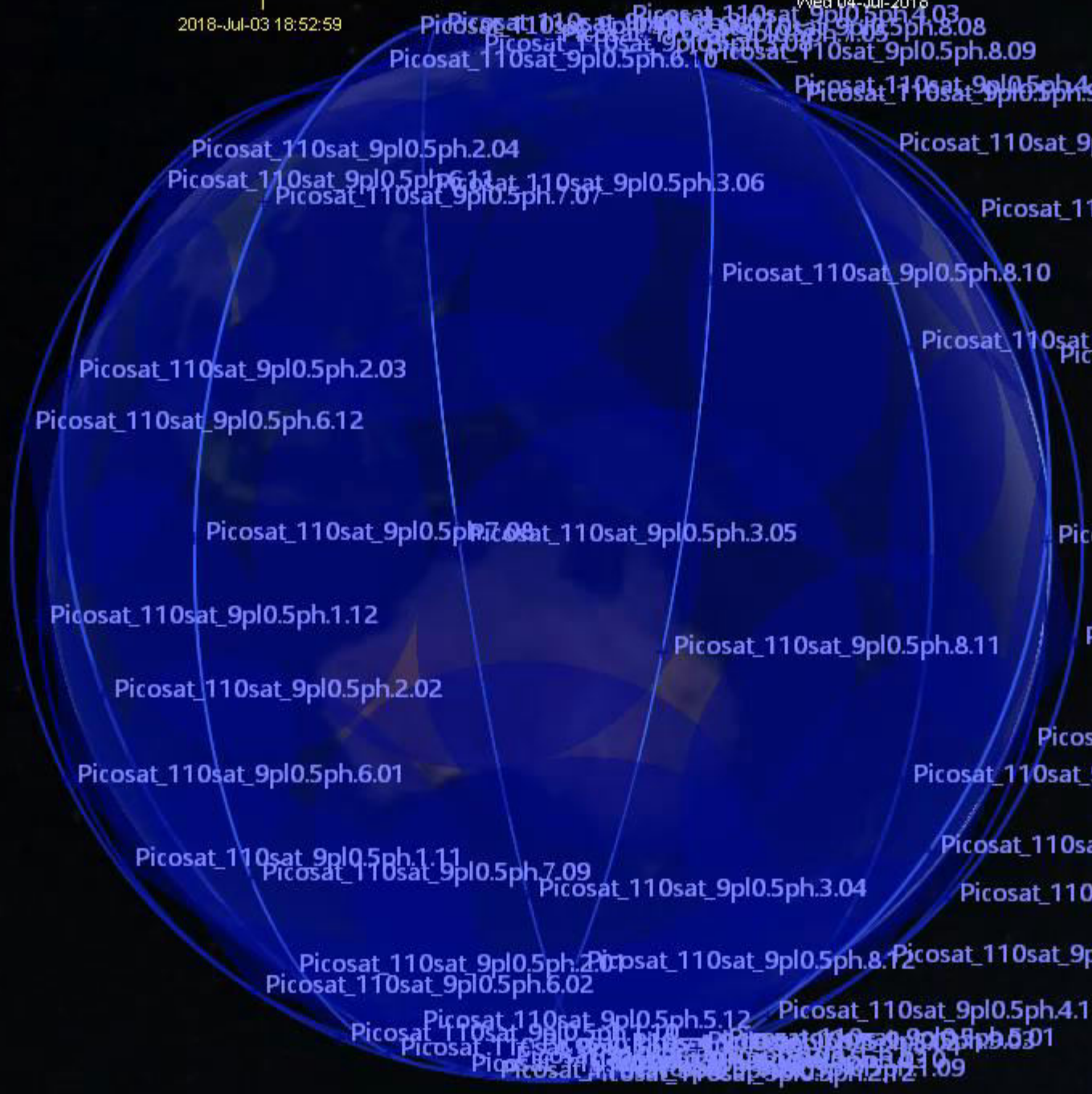


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Wed 04-Jul-2018



Mercury





Contact

Stuart McAndrew

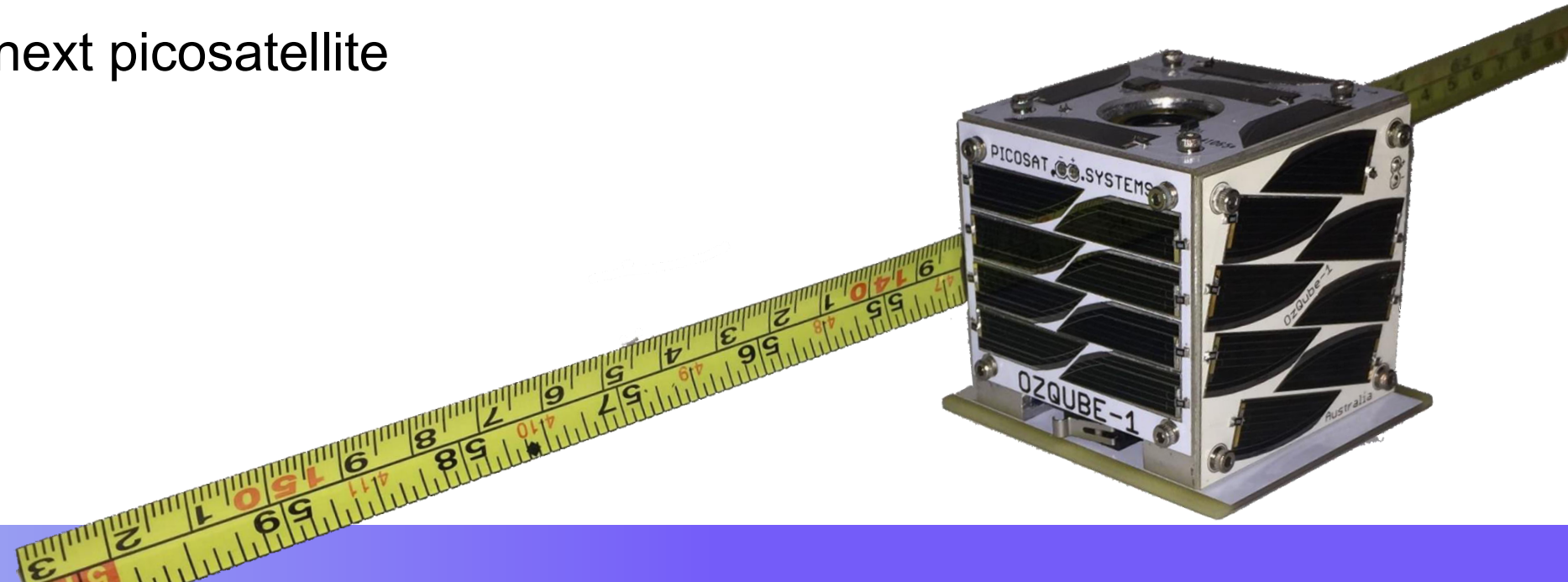
CTO & Cofounder

stuart@picosat.systems

@picosatsystems

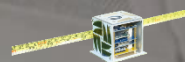


Let us build your next picosatellite mission!





Extra Slides



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Zero-G Collaboration

Press release & video: www.icrar.org/picosat

